

**Amendments to the Specification:**

Please replace paragraph [0003] with the following amended paragraph:

[0003] To solve the above problem, a remote actuator is provided on the handlebar and is connected to the lockout mechanism through a control cable. The cable system should be routed as directly as possible to minimize friction. By minimizing friction in the cable system, the actuating force at the handlebar is also minimized. Advantageously, the control cable is protected from contaminants to minimize friction. Further, to reduce cost, it is desirable to provide a remote actuator that is retrofitted to an existing control device local to the suspension system. This may be accomplished by replacing the actuator or knob of the existing control device with a simple spool connectable to the control cable.

Please replace paragraph [0004] with the following amended paragraph:

[0004] A cable guide 100 for a remote actuated suspension system has been previously provided as shown in FIG. 1, however, there are several drawbacks to the system. The guide 100 includes a ~~first~~ redirect spool 110 for changing the direction of the control cable 116 extending from a ~~second spool~~ lever 118 located on a top 130 of the fork. The ~~first~~ spool 110 is located at a very high stress point 112 on a crown 114. Further, the 180-degree change in direction of the control cable between the ~~first and second spools~~ lever and the spool, adds friction, thereby reducing the life of the control cable. ~~The additional spool 110 also makes the design more costly and complicated.~~